# Foundations of Bayesian NLP MSc Artificial Intelligence

Lecturer: Wilker Aziz Institute for Logic, Language, and Computation

2018

# The problem with $\ensuremath{\mathsf{MLE}}$

Motivating example from Liang and Klein (2007)

mixture of Gaussians trained via EM

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- on heldout set
- preferably via cross-validation

#### Can you see limitations of this approach?

- availability of data
- representativeness of heldout set
- discrete optimisation: combinatorial search over models

# NLP1

#### Preliminaries

Bayesian modelling

Applications

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#### • N observations $\mathbf{x} = \langle x_1, \dots, x_N \rangle$

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$$\theta = \langle \theta_1, \dots, \theta_K \rangle$$

► Collection of parameter vectors  $\boldsymbol{\theta} = \langle \theta^{(1)}, \dots, \theta^{(C)} \rangle$ 



Let's assume x to be 1 of K, and z to be 1 of C

categorical likelihood



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 $Z_i \sim \mathcal{U}(C)$   $X_i | \boldsymbol{\theta}, \mathbf{z}_{-i}, z_i = c \sim \operatorname{Cat}(\theta^{(c)})$ (1)

What is a sensible conditional distribution  $X|\theta^{(c)} \sim \operatorname{Cat}(\theta^{(c)})$ ?







$$c = 1$$
 (the blue cluster),  $K = 4$ 



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c = 1 (the blue cluster), K = 4

Can you make any assumptions before observing data?

What does Bayes rule tell you?

$$\underbrace{P(h|d)}_{\text{posterior}} =$$

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- the evidence tells you how well your model *M* explains the data, i.e. *P(d)* is actually *P(d|M)*
#### Bayes rule

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- the prior tells you how much h conforms to expectations about what a good hypothesis looks like regardless of observed data;
- ► the evidence tells you how well your model *M* explains the data, i.e. *P(d)* is actually *P(d|M)*
- the posterior updates our beliefs about hypotheses in light of observed data.

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- all hypotheses are equally likely a priori;
- can be approached by coordinate ascent methods;
- local optimality guarantees;

#### All the same a priori



#### Before data, MLE is equally happy with the hypotheses on the left

Maximum a posteriori

$$h^{\star} = \underset{h}{\operatorname{arg\,max}} P(d|h)P(h)$$
$$= \underset{h}{\operatorname{arg\,max}} \log P(d|h) + \log P(h)$$

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"I read before that Bayesian priors are just like regularisers, I even know that a Gaussian prior is just  $L_2$  regularisation"

- that only covers the specification of a prior
- Bayesian modelling does not end at prior specification you need the crucial part: posterior inference

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Preliminaries

#### Bayesian modelling Dirichlet-Multinomial model

Applications



In a Bayesian model, parameters are no different from data

they are random variables much like data



In a Bayesian model, parameters are no different from data

- they are random variables much like data
- only they are not observed



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We will study an example that illustrates important concepts Dirichlet-Multinomial model

### Dirichlet distribution

A distribution over the open simplex of K-dimensional vectors we denote the simplex by

$$\Delta_{K-1} = \left\{ \theta \in \mathbb{R}_{>0}^{K} : \sum_{k=1}^{K} \theta_{k} = 1 \right\} \subseteq \mathbb{R}_{>0}^{K}$$
(5)







#### Count vector

For observations x, where  $x_i$  is 1 of K define  $n^{(\mathbf{x})}$  as the K-dimensional vector such that

$$n_k = \sum_{i=1}^{N} [x_i = k]$$
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$$n_k = \sum_{i=1}^N [x_i = k] \tag{6}$$

Example: for K = 3 and N = 6

$$\mathbf{x} = \langle x_1 = 2, x_2 = 3, x_3 = 1, x_4 = 2, x_5 = 2, x_6 = 3 \rangle$$
  
$$n^{(\mathbf{x})} =$$

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$$n^{(\mathbf{x})} = \langle n_1 = 1, n_2 = 3, n_3 = 2 \rangle$$

#### Gamma function

A generalisation of the factorial function to  $\ensuremath{\mathbb{R}}$ 

$$\Gamma(z) = \int_0^\infty \epsilon^{z-1} \exp(-\epsilon) d\epsilon$$
(7)

Properties

• 
$$\Gamma(n) = (n-1)!$$
 for positive integer  $n$   
•  $\Gamma(z) = (z-1)\Gamma(z-1)$ 

# **Dirchlet-Multinomial**



#### Model

$$\begin{aligned} \theta &| \beta \sim \text{Dir}(\beta) \\ X_i &| \theta \sim \text{Cat}(\theta) \quad \text{for } i = 1, \dots, N \end{aligned}$$
 (8)

#### **Dirchlet-Multinomial**



Model

$$\begin{array}{l}
\theta|eta \sim \operatorname{Dir}(eta)\\
X_i|\theta \sim \operatorname{Cat}(\theta) \quad \text{for } i = 1, \dots, N
\end{array}$$
(8)

Joint distribution

$$P(\mathbf{x}, \theta | \beta) = P(\theta) P(\mathbf{x} | \theta)$$
  
= Dir(\theta | \beta) Mult(n^{(\mathbf{x})} | \theta, N) (9)

# Multinomial likelihood

For  $\theta \in \Delta_{K-1}$ 

$$P(\mathbf{x}|\theta) = \text{Mult}(n^{(\mathbf{x})}|\theta, N)$$

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#### Multinomial likelihood For $\theta \in \Delta_{K-1}$

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$$= \frac{N!}{\prod_{k=1}^{K} n_k!} \prod_{k=1}^{K} \theta_k^{n_k}$$
$$= \frac{\Gamma(\sum_{k=1}^{K} n_k + 1)}{\prod_{k=1}^{K} \Gamma(n_k + 1)} \prod_{k=1}^{K} \theta_k^{n_k}$$

#### Multinomial likelihood For $\theta \in \Delta_{K-1}$

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$$(10)$$

Example: for K = 3 and N = 6

$$\theta = \langle \theta_1 = 0.2, \theta_2 = 0.3, \theta_3 = 0.5 \rangle$$
  

$$\mathbf{x} = \langle x_1 = 2, x_2 = 3, x_3 = 1, x_4 = 2, x_5 = 2, x_6 = 3 \rangle$$
  

$$n^{(\mathbf{x})} = \langle n_1 = 1, n_2 = 3, n_3 = 2 \rangle$$

$$P(\mathbf{x}|\theta) = \frac{\Gamma(\ldots)}{\prod \cdots} \theta_1^1 \times \theta_2^3 \times \theta_3^2$$

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# Dirichlet prior

For  $\beta \in \mathbb{R}_{>0}^K$ 

$$\operatorname{Dir}(\boldsymbol{\theta}|\boldsymbol{\beta}) = \frac{\Gamma(\sum_{k=1}^{K} \beta_k)}{\prod_{k=1}^{K} \Gamma(\beta_k)} \prod_{k=1}^{K} \theta_k^{\beta_k - 1}$$

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$$\propto \prod_{k=1}^{K} \theta_k^{\beta_k - 1}$$
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We call

$$\int_{\Delta_{K-1}} \prod_{k=1}^{K} \theta_k^{\beta_k - 1} = \frac{\prod_{k=1}^{K} \Gamma(\beta_k)}{\Gamma(\sum_{k=1}^{K} \beta_k)}$$

the Dirichlet normaliser

Posterior

#### $P(\boldsymbol{\theta}|\mathbf{x},\beta) \propto$

#### Posterior

 $P(\boldsymbol{\theta}|\mathbf{x},\boldsymbol{\beta}) \propto P(\mathbf{x}|\boldsymbol{\theta})P(\boldsymbol{\theta}|\boldsymbol{\beta})$








$$\begin{split} P(\boldsymbol{\theta}|\mathbf{x},\boldsymbol{\beta}) &\propto P(\mathbf{x}|\boldsymbol{\theta})P(\boldsymbol{\theta}|\boldsymbol{\beta}) \\ &\propto \underbrace{\frac{\Gamma(\sum_{k=1}^{K}n_{k}+1)}{\prod_{k=1}^{K}\Gamma(n_{k}+1)}\prod_{k=1}^{K}\theta_{k}^{n_{k}}}_{\mathrm{Mult}(n^{(\mathbf{x})}|\boldsymbol{\theta})} \times \underbrace{\frac{\Gamma(\sum_{k=1}^{K}\beta_{k})}{\prod_{k=1}^{K}\Gamma(\beta_{k})}\prod_{k=1}^{K}\theta_{k}^{\beta_{k}-1}}_{\mathrm{Dir}(\boldsymbol{\theta}|\boldsymbol{\beta})} \\ &\propto \prod_{k=1}^{K}\theta_{k}^{n_{k}} \times \prod_{k=1}^{K}\theta_{k}^{\beta_{k}-1} \\ &= \prod_{k=1}^{K}\theta_{k}^{n_{k}+\beta_{k}-1} \end{split}$$

$$P(\theta|\mathbf{x},\beta) \propto P(\mathbf{x}|\theta)P(\theta|\beta)$$

$$\propto \underbrace{\frac{\Gamma(\sum_{k=1}^{K} n_k + 1)}{\prod_{k=1}^{K} \Gamma(n_k + 1)} \prod_{k=1}^{K} \theta_k^{n_k}}_{\operatorname{Mult}(n^{(\mathbf{x})}|\theta)} \times \underbrace{\frac{\Gamma(\sum_{k=1}^{K} \beta_k)}{\prod_{k=1}^{K} \Gamma(\beta_k)} \prod_{k=1}^{K} \theta_k^{\beta_k - 1}}_{\operatorname{Dir}(\theta|\beta)}}_{\operatorname{Dir}(\theta|\beta)}$$

$$\propto \prod_{k=1}^{K} \theta_k^{n_k} \times \prod_{k=1}^{K} \theta_k^{\beta_k - 1}$$

$$= \prod_{k=1}^{K} \theta_k^{n_k + \beta_k - 1} \propto \operatorname{Dir}(\theta|n^{(\mathbf{x})} + \beta)$$

$$\begin{split} P(\boldsymbol{\theta}|\mathbf{x},\boldsymbol{\beta}) &\propto P(\mathbf{x}|\boldsymbol{\theta})P(\boldsymbol{\theta}|\boldsymbol{\beta}) \\ &\propto \underbrace{\frac{\Gamma(\sum_{k=1}^{K}n_{k}+1)}{\prod_{k=1}^{K}\Gamma(n_{k}+1)}\prod_{k=1}^{K}\theta_{k}^{n_{k}}}_{\mathrm{Mult}(n^{(\mathbf{x})}|\boldsymbol{\theta})} \times \underbrace{\frac{\Gamma(\sum_{k=1}^{K}\beta_{k})}{\prod_{k=1}^{K}\Gamma(\beta_{k})}\prod_{k=1}^{K}\theta_{k}^{\beta_{k}-1}}_{\mathrm{Dir}(\boldsymbol{\theta}|\boldsymbol{\beta})} \\ &\propto \prod_{k=1}^{K}\theta_{k}^{n_{k}} \times \prod_{k=1}^{K}\theta_{k}^{\beta_{k}-1} \\ &= \prod_{k=1}^{K}\theta_{k}^{n_{k}+\beta_{k}-1} \propto \mathrm{Dir}(\boldsymbol{\theta}|n^{(\mathbf{x})}+\boldsymbol{\beta}) \end{split}$$

Thus

$$P(\theta|\mathbf{x},\beta) = \underbrace{\prod_{\substack{1 \text{ normaliser of Dir}(n^{(\mathbf{x})}+\beta)}} \prod_{k=1}^{K} \theta_k^{n_k+\beta_k-1}$$
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Thus

$$P(\theta|\mathbf{x},\beta) = \underbrace{\frac{\Gamma(N + \sum_{k=1}^{K} \beta_k)}{\prod_{k=1}^{K} \Gamma(n_k + \beta_k)}}_{\frac{1}{\text{normaliser}} \text{ of } \text{Dir}(n^{(\mathbf{x})} + \beta)} \prod_{k=1}^{K} \theta_k^{n_k + \beta_k - 1}$$
(12)

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#### Posterior predictive distribution

Suppose a new data point  $x_{N+1} = j$  is available



$$P(x_{N+1} = j | \mathbf{x}, \beta) = \int_{\Delta_{K-1}} P(\theta, x_{N+1} | \mathbf{x}, \beta) d\theta$$

 $x_{N+1}$  is independent of  ${\bf x}$  given  $\theta$ 

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$$= \int_{\Delta_{K-1}} \theta_j \times d\theta \end{split}$$



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$$= \int_{\Delta_{K-1}} \theta_j \times \underbrace{\frac{\Gamma(N + \sum_{k=1}^K \beta_k)}{\prod_{k=1}^K \Gamma(n_k + \beta_k)}}_{\text{constant wrt } \theta} \prod_{k=1}^K \theta_k^{n_k + \beta_k - 1} d\theta$$
$$= \underbrace{\frac{\Gamma(N + \sum_{k=1}^K \beta_k)}{\prod_{k=1}^K \Gamma(n_k + \beta_k)}}_{\text{constant wrt } \theta} \int_{\Delta_{K-1}} \theta_j \times d\theta$$

$$P(x_{N+1} = j | \mathbf{x}, \beta) = \int_{\Delta_{K-1}} \underbrace{\frac{P(x_{N+1} = j | \theta)}{\mathsf{likelihood}}}_{\mathsf{posterior}} \underbrace{P(\theta | \mathbf{x}, \beta)}_{\mathsf{posterior}} \mathrm{d}\theta$$
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$$= \frac{\Gamma(N + \sum_{k=1}^{K} \beta_k)}{\prod_{k=1}^{K} \Gamma(n_k + \beta_k)} \underbrace{\frac{1}{\sum_{k=1}^{K} \beta_k}}_{\mathsf{Dir normaliser}}$$

$$\begin{split} P(x_{N+1} &= j | \mathbf{x}, \beta) = \int_{\Delta_{K-1}} \underbrace{\frac{P(x_{N+1} = j | \theta)}{\mathsf{likelihood}} \underbrace{\frac{P(\theta | \mathbf{x}, \beta)}{\mathsf{posterior}}}_{\mathsf{posterior}} \mathrm{d}\theta \\ &= \frac{\Gamma(N + \sum_{k=1}^{K} \beta_k)}{\prod_{k=1}^{K} \Gamma(n_k + \beta_k)} \underbrace{\int_{\Delta_{K-1}} \theta_j^{n_j + \beta_j} \prod_{k \neq j} \theta_k^{n_k + \beta_k - 1} \mathrm{d}\theta}_{\mathsf{Dir normaliser}} \\ &= \frac{\Gamma(N + \sum_{k=1}^{K} \beta_k)}{\prod_{k=1}^{K} \Gamma(n_k + \beta_k)} \underbrace{\frac{\Gamma(N + \sum_{k=1}^{K} \beta_k + 1)}{\Gamma(N + \sum_{k=1}^{K} \beta_k + 1)}}$$

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$$= \frac{n_j + \beta_j}{N + \sum_{k=1}^{K} \beta_k}$$

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Dirchlet-Multinomial (overview)



Joint distribution

$$P(\mathbf{x}, \theta | \beta) = P(\theta) P(\mathbf{x} | \theta)$$
  
= Dir(\theta|\beta) Mult(n<sup>(x)</sup>|\theta, N) (13)

Posterior

$$P(\theta|\mathbf{x},\beta) = \text{Dir}(\theta|n^{(\mathbf{x})} + \beta)$$
(14)

Predictive posterior

$$P(x_{N+1} = j | \mathbf{x}, \beta) = \frac{n_j + \beta_j}{N + \sum_{k=1}^K \beta_k}$$
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(17)

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# Summary

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- no point estimates, we use all possible model parameters
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- MLE is memoryless: there is one fixed θ, no matter how much more data you see, θ will never change

# NLP1

Preliminaries

Bayesian modelling

Applications

Wilker Aziz NLP1 2018





Define counts based on joint assignments to  $\mathbf{x}_{-i}, \mathbf{z}_{-i}$ 

$$n_{c,k} = \sum_{j \neq i} [z_j = c] [x_j = k]$$
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unlike it may seem, it does not mean to promote diversity! Let's see whether the posterior is *peaked* 

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what about preferring to use fewer components?

#### Sparse prior over mixing weights

Say we have 10 components, how do you want to use them?







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$$P(z_i = c | \mathbf{x}, \mathbf{z}_{-i}, \alpha, \beta) \text{ note that } \begin{cases} z_{i-1} = b \\ z_{i+1} = d \end{cases} \text{ is in } \mathbf{z}_{-i}$$



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We draw from the posterior  $P(\mathbf{z}|\mathbf{x})$  via a Markov chain of random states  $Y_1, \ldots, Y_T$  where  $P(y_t|y_{< t}) = P(y_t|y_{t-1})$ 

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- applying each of P<sub>k</sub> in turn or choosing P<sub>k</sub> at random produces a P that satisfies the necessary conditions

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  - ▶ resample  $Z_i \sim P(z_i | \mathbf{x}_{-i}, \mathbf{z}_{-i})$ only variables in the Markov blanket of  $z_i$  play a role that's why this is feasible
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When we have collected a large number T of samples

we can summarise the distribution and/or make decisions

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### Beyond

For more on latent variable modelling, especially with structured data

- take NLP2
- though most of it will be *frequentist* (for very good reasons!)

For more on Bayesian modelling, approximate inference, and probabilistic modelling with neural networks

- take ML4NLP
- though MCMC will not be the method of choice, instead we will look into variational inference
- and we will need to count on optimisation =0
- though with a nice twist ;)

### References I

Wilker Aziz NLP1 2018